



Baby-LIN-MB-II

Multibus simulation device with multi interface options



Product description

The Baby-LIN-MB-II is a modular RS-232/Ethernet to LIN- and CAN-Bus gateway, which allows to control LIN- or CAN-Bus driven ECU's from any host (e.g. PLC) equipped with RS232 or Ethernet.

The Baby-LIN-MB-II features slots for up to 2 piggyback extensions. These MIF (mounted interface) extensions allow a **modularisation** of the device. Therefor the device can meet strongly varying requirements(e.g. up to 6 independent LIN-Bus interfaces). The following MIF modules are available:

- MIF-LIN: adds 2 additional LIN-Bus interfaces
- · MIF-DIO: adds 6 shared digital inputs/outputs
- MIF-CAN-FD: adds 2 optional CAN-FD interfaces

More MIF interfaces are in development but not yet available for purchase.

The basic version of the Baby-LIN-MB-II hardware is delivered with:

- · 1 LIN-Bus interface
- 1 additional LIN-Bus available on hardware (requires activation via voucher code)
- 1 CAN-HS-Bus available on hardware (requires activation via voucher code)
- · 1 digital input
- 1 digital output
- 1 switchable LIN bus power output (with the correct wiring, it can be used as digital output as well)
- · 2 free MIF slots

Please do not hesitate to request **custom configurations** of the base device and MIF extensions.

The LIN- and CAN-Bus configurations are defined in a custom SDF. The process can be controlled by a simple **ASCII command protocol**, issued via the built-in RS-232 or Ethernet interface. The command protocol uses an extensible **plug-in system**. Therefor new plug-ins can be purchased with special new features or customer specific commands.

A Linux driven host CPU allows for easy adaption of network protocols and remote support options.

A modern **web interface** is available and accessible with any browser as long as the device is connected to the local network. Amongst others is provides the following features:

· Information about the installed components

- · Easy upload and deletion of SDFs
- · View and edit the system configuration
- · Online manual
- · Firmware update

Multiple SDF's can be stored on the **internal flash drive**. At least 50 MB of the 4 GB flash drive are reserved for user specific SDF's.

An **USB 2.0 host** interface is integrated in the device. USB drives and USB card readers with FAT file systems can be used. This allows for easy update and SDF upload mechanisms. Additionally log data can be written and easily transferred the PC.

The basic configuration of the device already integrates 1 digital input and 1 electrically isolated digital output. Additionally a switched LIN supply output is available which can be used to switch the LIN bus supply on and off.

An integrated **UPS** (uninterruptible power supply) allows the save shutdown of the system during power fail events or keeps the system running on short power drops.

A compatibility adapter is separately available to convert the new Sub-D-25 connector pinning to the old 2x Sub-D-9 connector pinning of the old Baby-LIN-MB.

The Baby-LIN-MB-II can handle LIN-Bus voltages in the range of 8-26VDC. All communication interfaces (LIN- and CAN-Bus, Ethernet, RS-232, Digital I/O) are galvanically isolated, eliminating interferences between the PC and the board electronics.

The Baby-LIN-MB-II unit includes its own 32-bit microcontroller, which takes care of all **time critical** tasks of the LIN- and CAN-Bus protocol.

Each pair of LIN-Bus interfaces is additionally supported by another dedicated microcontroller.

The device firmware is field updateable, so the changes of bus specification or upcoming new system features can be adapted easy.

The Baby-LIN-MB-II supports **SDF-V3**. This new generation of SDF allows new features like multiple bus sections, conditional macro commands, new system variables, new CRC functions and sub macro calls.

Operation mode

Any situation that requires communication with a LIN or CAN device is a potential field of application for a Baby-LIN-MB-II. It is a versatile tool that can be used in research laboratories, test departments and production (EOL applications).

The Baby-LIN-MB-II allows for different operation modes to support typical use cases like:

- Monitor and log all frames on the bus without the need for a SDF.
 If a SDF is available signal values can also be monitored.
- Control the bus via the LINWorks software or customer specific applications by using the Baby-LIN-DLL.
- Program and store free programmable command sequences in the Baby-LIN-MB-II to run it as a stand-alone device without the need for a PC. Thus you can run a bus driven ECU in a durability test or EOL applications without any PC connected.



Website: www.lipowsky.com





Simulation modes

The Baby-LIN-MB-II is able to simulate different configurations of LIN- and CAN-Bus nodes. It is possible to **simulate any number of nodes** ranging from none to all.These are some typical configurations:

- LIN-Bus: Simulate the LIN-Bus master to operate slave nodes.
- · LIN-Bus: Simulate any number of LIN-Bus slave nodes.
- LIN-Bus: Simulate all nodes and therefor the complete communication on the bus.
- · CAN-Bus: Simulate any number of CAN-Bus nodes.
- LIN- and CAN-Bus: Simulate all but one node and realize a resid-
- LIN- and CAN-Bus: Simulate no node to monitor the bus communication only.

Simulations for the LIN- and CAN-Bus can be done simultaneously.

LIN- and CAN-Bus properties

The used LIN driver supports bus voltages of 8-26 VDC and can be used up to 115200 Baud. That way even nodes that operate outside the standard limits of the LIN specifications can be controlled with the Baby-LIN-MB-II. Supported LIN-versions are V.1.2, V.1.3,...V.2.2. The pull-up resistor of the LIN-Bus driver is switched to 1 kOhm, if the master node is emulated and to 30 kOhm, if only slave nodes are emulated.

The CAN-Bus of the Baby-LIN-MB-II is designed as a high-speed inter-face according to ISO-11898 with a SN65HVD251 driver.

The maximum supported signal cable length of the LIN- and CAN-Bus is 30m but can be less, depending on the bus assembly.

LINWorks suite

The purchase of a Baby-LIN-MB-II includes the license to download the **LINWorks** suite. This suite is a collection of PC software that supports you

during the whole workflow.

The **LDFEdit** allows the inspection, creation and edit of a LDFile (LIN Description File).

The **SessionConf** allows the inspection, creation and edit of a SDFile (Session Description File) and features a file import for LDFiles (for LINBus simulation) and DBC files (for CAN-Bus simulation). It defines everything needed for a complete simulation of each available bus, e.g. which nodes on each bus are available and which nodes should be simulated by the Baby-LIN-MB-II. Moreover it allows defining an application logic. This programming ability is available for each device out of the box.

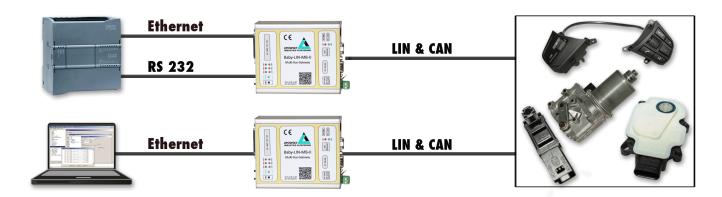
The **SimpleMenu** is used to establish a connection to the Baby-LIN-MB-II and upload SDFiles, change the device target configuration, control the bus and monitor the frames and signals on the bus. Even without a LD-File, DBC file or SDFile the bus can be monitored and the frames can be logged.

The **Baby-LIN-DLL** allows customers to create their own application and use all features of the Baby-LIN-MB-II like controlling and monitoring the LIN- and CAN-Bus interfaces. The **Baby-LIN-DLL** is a native **C/C++** DLL. It is available for **Windows**, **Linux** and **RaspberryPi**. Wrapper for **NET**, **Python**, **VB6** and **LabView** are available. Of course we provide examples for all supported languages.

The **LogViewer** can show and convert the log files of the Baby-LIN-MB-II as well as the SimpleMenu.

The **Baby-LIN-MB-Tool** allows to access many features of the Baby-LIN-MB-II. It can help to search and identify Baby-LIN-MB-IIs, change the **network configuration** and select different modes. Scripts using the **ASCII command protocol** can be executed, debugged and logged. The simulation mode allows to **simulate** certain behaviors of the Baby-LIN-MB-II to test custom applications. Additionally the Baby-LIN-MB-Tool features many different **logging** capabilities.

The **LINWorks** software runs on 32 and 64 bit Windows versions.







Technical Specifications

Device

- · CPU: ARM Cortex-A5, 528 MHz
- · Memory: 256 MB DDR-RAM
- Power supply: 8-32 VDC
- Power supply via 3 pin connector (MC 1,5/3-ST-3,81)(*1)
- · Maximum current consumption: 420 mA @ 24 VDC
- · Integrated UPS (uninterruptible power supply)
- · UPS charge duration: about 22 seconds
- · UPS discharge duration: about 2 seconds
- · Inrush current: 1,22 A
- · Galvanic isolation of all communication interfaces (LIN- and CAN-Bus, Ethernet, RS-232, Digital I/O) Exception: The supply and ground lines of all LIN-Channels are connected respectively with each other to reduce the number of lines. This configuration can be changed via jumpers.
- · 2 LEDs: Signal device states
- · 2 device specific push buttons
- 6 bicolor LEDs: Signal bus and error states
- · Real-time clock (battery-backed) (*1) The hardware revision A used a 2-pin plug (MSTB 2,5/ 2- ST-5,08) and the earth connection was available via a 6,3 mm earth pin.

Interface: LIN

- · Up to 6 LIN-Bus interfaces available
- · 1 LIN-Bus interface available by default
- · 1 LIN-Bus interface optionally available on hardware but not activated, voucher code required
- · 4 LIN-Bus interfaces available through hardware modules, additional hardware extensions required
- · LIN-Bus connection via 25 pin Sub-D connector
- · LIN-Bus supply voltage: 8-26 VDC
- · LIN-Bus baud rate: up to 115200 Baud (Support of protocols outside of the LIN specification)
- Supported LIN versions: V1.2, V1.3,...V2.2
- Supported LIN related protocols: Cooling and SAE J2602

- · Maximum signal cable length for LIN-Bus: 30 m
- · Switched LIN supply output

Interface: CAN

- · 1 CAN-Bus as high speed interface (CAN-HS) according to ISO-11898 available on hardware but not activated, voucher code reauired
- Used CAN-Bus driver for CAN-HS: SN65HVD251
- · CAN-HS-Bus connection via 25 pin Sub-D connector
- · Maximum baudrate: CAN-HS: 1 MBit/s
- · Maximum signal cable length for CAN-Bus: 30m

Interface: USB Host

- USB 2.0 interface via USB 2.0 type A connector
- · Max current: 500 mA
- · Supported file system: FAT-32, FAT-16

Interface: Ethernet

- · Ethernet via RJ-45 connector
- · Transfer rate: 10/100 MBit
- · Auto MDI-X feature
- · Command protocol: TCP-IP socket on port 10002
- · Web interface for device events, system information as well as easy SDF upload

Interface: RS232

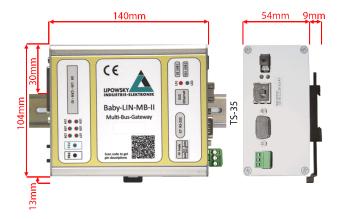
- · Serial connection via Sub-D-9 female connector
- · Data rate: 9600 Baud
- · Data bits, parity bit, stop bit: 8-N-1

Interface: Digital I/O

- · 1 digital input
- 1 electrically isolated digital output (0V 24V, max. 190mA)
- 1 switchable power output (12 V- 30 V, Max. 700 mA)
- Digital I/O available via Sub-D-25 female connector

Case

- · Degree of protection: IP20
- Operating temperature: -20° +60° Celsius
- Weight: 440 g
- Case dimensions [mm]: 124 x 104 x 54 (L x W x H) Elements like connectors, buttons, and the top hat rail mounting adapter are not included.
- · Mounting: Top hat rail (TS 35):





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Advice

The complete technical specifications can be found in our user manual. It contains amongst other details the following information:

- Connector pin assignment
 Firmware description
- Protocol information
- Electrical characteristics SDFile description
- Migration information
- Electrical characteristics Software description FAQ

The user manual can be found in our LINWorks download package.

Hardware requirements

The following hardware is required to operate the Baby-LIN:

Requirement	Purpose	
A PC with about 200 MB free hard drive space	Required for the installation of the LINWorks software. Please check the software requirements	
	and use cases.	
A free com port	Required only, if the Baby-LIN-MB-II is controlled using the ASCII command protocol via the RS-	
	232 interface.	
Access to the local network	Required only, if the Baby-LIN-MB-II is controlled using the ASCII command protocol via the Eth-	
	ernet interface or it is controlled by the SimpleMenu or the Baby-LIN-DLL.	
A USB mass storage device	Required to transfer SDFiles and firmware updates to the Baby-LIN-MB-II. Can be used to log	
	frames.	
Power supply: 8-32 VDC, min. 2A	Voltage supply of the Baby-LIN-MB-II.	

Software requirements

The LINWorks software requires one of the following operating systems:

- · Windows XP
- · Windows Vista (32 and 64 Bit)
- Windows 7 (32 and 64 Bit)
- Windows 8 (32 and 64 Bit)
- · Windows 10 (32 and 64 Bit)



The Baby-LIN-DLL is available for Linux. The exact requirements are available upon request.

Some additional tools available in the LINWorks software suite require an installed .NET Framework v4.0. To install LINWorks components administration privileges are required.

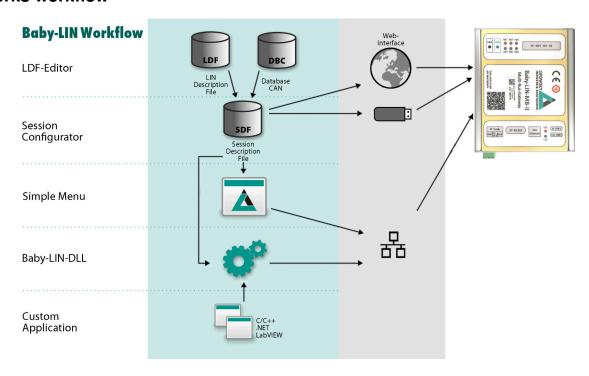


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LINWorks workflow



Scope of delivery

The delivery of a Baby-LIN-MB-II systems includes the following components:

- Baby-LIN-MB-II device
- One 3-pin plug with screw connection (MC 1,5/ 3-ST-3,81)(*1)
- Download license for the LINWorks Suite (includes LINWorks PC software, example files and documentations)

(*1) The hardware revision A used a 2-pin plug (MSTB 2,5/2-ST-5,08) and the earth connection was available via a 6,3 mm earth pin.

Ordering information

Item number	Item	Description		
8001036	Baby-LIN-MB-II	Multibus simulation device with multi interface options. Features: 1 LIN channel, 1 digital input, 2 digital		
		outputs.		
8000930	Baby-LIN-MB-II-4L	Multibus simulation device with multi interface options and pre-installed components. The LIN2 option and the MIF-LIN increase the number of LIN channels to a total number of 4. Features: 4 LIN channel, 1 digital input, 2 digital outputs. Content: 1 x Baby-LIN-MB-II, 1 x Option BL-MB-II LIN2, 1 x MIF-LIN		
8000931	Baby-LIN-MB-II-D	Multibus simulation device with multi interface options and pre-installed components. The MIF-DIO adds 6 shared digital inputs/outputs. Features: 1 LIN channel, 1 digital input, 2 digital outputs, 6 shared digital inputs/outputs. Content: 1 x Baby-LIN-MB-II, 1 x MIF-DIO		
8000932	Baby-LIN-MB-II-6L	Multibus simulation device with multi interface options and pre-installed components. The LIN2 option and the two MIF-LIN increase the number of LIN channels to a total number of 6. Features: 6 LIN channel, 1 digital input, 2 digital outputs. Content: 1 x Baby-LIN-MB-II, 1 x Option BL-MB-II LIN2, 2 x MIF-LIN		
8000933	Baby-LIN-MB-II-4LD	Multibus simulation device with multi interface options and pre-installed components. The LIN2 option and the MIF-LIN increase the number of LIN channels to a total number of 4. The MIF-DIO adds 6 shared digital inputs/outputs. Features: 4 LIN channel, 1 digital input, 2 digital outputs, 6 shared digital inputs/outputs. Content: 1 x Baby-LIN-MB-II, 1 x Option BL-MB-II LIN2, 1 x MIF-LIN, 1 x MIF-DIO		









Advice
Each device includes a download license for the LINWorks application suite. This PC software can be downloaded using our client portal.ipowsky.de



TipCountry of origin:
Customs tariff number:

Germany 90308900

Optional hardware components

Item number	Item	Description			
8000872	Option BL-MB-II MIF-LIN	MIF-Module for Baby-LIN-MB-II to add 2 LIN interfaces including SDF-V3 support.			
8000890	Option-BL-MB-II-MIF-DIO	MIF-Module for Baby-LIN-MB-II to add 6 shared digital inputs/outputs Warning If the MIF-DIO is installed, the LIN supply detection lines of the first two LIN channels cannot be used anymore. Their connector pins are used by the MIF-DIO. Version incompatitibility The MIF-DIO module for Baby-LIN-MB-II Rev. C or later can be installed by the			
8002100	Option BL-MB-II MIF-CAN-FD	customer. The installation for Baby-LIN-MB-II Rev. A or B can only be executed by Lipowsky Industrie-Elektronik GmbH. Please contact us to prepare the mailing of your Baby-LIN-MB-II. MIF-Module for Baby-LIN-MB-II adds 2 additional CAN channels which can be each uses as high-speed CAN or CAN-FD (up to 8Mbit). Warning The MIF-CAN-FD and the LIN channels share the same ground potencial. To use the channels on the MIF-CAN-FD as high-speed or FD bus, additional			
8000916	BLMB-II-Dual-SUB-D9	voucher codes are required, which are listed in the next section. Compatibility adapter to offer 2 Sub-D-9 connectors on the Baby-LIN-MB-II to recover the original Baby-LIN-MB pinning. Includes mouting materials. Warning The basic version of the Baby-LIN-MB did only offer one LIN-bus interface, one digital inputand one digital output. It is not possible to use the additional LIN- or CAN-Bus interfaces orl/Os of the Baby-LIN-MB-II or any MIF extensions, if you use this adapter.			
2900150	3V CR2430 Lithium button cell	This button cell is used to power the RTC clock of the Baby-LIN-MB-II. A fresh cell can power the RTC clock for over 7Years years.			
3020795	MSTB 2,5/ 2-ST-5,08	2-pin plug component, screw connection with tension sleeve. Cable outlet parallel to plugin direction. Screw direction vertical to plugin direction. Used by hardware revision A of the Baby-LIN-MB-II.			
3021303	MC 1,5/ 3-ST-3,81	3-pin plug component, screw connection with tension sleeve. Cable outlet parallel to plugin direction. Screw direction vertical to plugin direction. Used since hardware revision B of the Baby-LIN-MB-II.			







Optional voucher codes

Item number	Item	Description		
8000870	Option BL-MB-II LIN-2	License code for Baby-LIN-MB-II to support the second LIN bus interface. Warning The second LIN bus channel shares the same memory with the first LIN bus channel. ASDFile that can be used for a single LIN bus channel may be to big to be used for both.		
8000871	Option BL-MB-II CAN-HS	License code for Baby-LIN-MB-II to activate the internal CAN-HS (High-Speed) support for the first CAN-Bus interface.		
8000810	Option BL-CAN-1-HS	License code for Baby-LIN-MB-II to activate CAN-HS (High-Speed) support for the first additional CAN-Bus interface. Only usable with the MIF-CAN-FD.		
8000990	Option BL-CAN-2-HS	License code for Baby-LIN-MB-II to activate CAN-HS (High-Speed) support for the second additional CAN-Bus interface. Only usable with the MIF-CAN-FD.		
8000991	Option BL-CAN-1-FD	License code for Baby-LIN-MB-II to activate CAN-FD (Flexible Data Rate) support for the first additional CAN-Bus interface. Attention: This voucher code can not be used without Option BL-CAN-1-HS.		
8000992	Option BL-CAN-2-FD	License code for Baby-LIN-MB-II to activate CAN-FD (Flexible Data Rate) support for the second additional CAN-Bus interface. Attention: This voucher code can not be used without Option BL-CAN-2-HS.		



Advice
All voucher codes can be converted using the option shop: www.optionshop.de/lipowsky

Optional software components

Item number Item		Description	
9004210	Customer specific installation.	Installation of customer specific SDFile version and/or installation of license activation key.	
9103010	LINWorks CD	The LINWorks archive with PC software for all Baby-LIN products on a physical medium (CD).	







Distributors

Area	Country	Distributor	Website	Phone	E-Mail
	*}	Hongke Technology Co. LTD	www.hkaco.com	+86 20 3874 4538	sales@hkaco.com
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		KMDATA Inc.	www.kmd.co.kr	+82 2 3281 0333	daniel@kmd.co.kr
	# *	ITHandel Inc.	www.ithandel.modoo.at	+82 10 4616 7079	ithandel01@naver.com
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		The Debug Store	www.thedebugstore.com	+44 1490 430526	sales@TheDebugStore.com
Worldwide		Lipowsky Industrie-Elektronik GmbH	www.lipowsky.com	+49 6151 935910	info@lipowsky.de

More details about our distributors can be found on our website under the heading <code>Distributors</code>.

Product disposal



After the product is no longer used, it must be disposed of separately from household waste at a designated recycling site. All kind of batteries must be removed from the device and disposed separately. Furthermore, you can also return the device to us for proper disposal, you only have to bear for the shipping costs. Please use this address:

Lipowsky Industrie-Elektronik GmbH Device disposal Römerstr. 57 64291 Darmstadt Germany

